



1 **Geostrophic drag law in conventionally**  
2 **neutral atmospheric boundary layer: simplified**  
3 **parametrization and numerical validation**

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8 **Abstract**

9 This study investigates the parameterization of the geostrophic drag law (GDL)  
10 for conventionally neutral atmospheric boundary layers (CNBLs). Utilizing  
11 large eddy simulations, we confirm that in CNBLs capped by a potential  
12 temperature inversion, the boundary-layer height scales as  $u_*/\sqrt{Nf}$ , where  
13  $u_*$  represents the friction velocity,  $N$  the free-atmosphere Brunt-Väisälä fre-  
14 quency, and  $f$  the Coriolis parameter. Additionally, we confirm that the wind  
15 gradients normalized by the Brunt-Väisälä frequency have universal profiles  
16 above the surface layer. Leveraging these physical insights, we derived analyti-  
17 cal expressions for the GDL coefficients  $A$  and  $B$ , correcting the earlier form of  
18 Zilitinkevich and Esau (2005, Q. J. R. Meteorol. Soc. 131: 1863-1892). These  
19 expressions for  $A$  and  $B$  have been validated numerically, ensuring their accu-  
20 racy in representing the geostrophic drag coefficient  $u_*/G$  ( $G$  is the geostrophic  
21 wind speed) and the cross-isobaric angle. This work extends the range for  
22 which the GDL has been validated up to  $u_*/G = [0.019, 0.047]$ . This further  
23 supports the application of GDL to CNBLs over a broader range of  $u_*/G$ ,  
24 which is useful for meteorological applications such as wind energy.

25 **Keywords** Atmospheric boundary layer · Conventionally neutral ·  
26 Geostrophic drag law · Large eddy simulations

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## 1 Introduction

The atmospheric boundary layer (ABL) is the lower part of the troposphere where most human activity and biological processes occur (Katul et al. 2011). The flow dynamics in the ABL are influenced by the Earth’s surface, Coriolis force, and thermal stratification (Monin 1970). When the potential temperature flux on the surface is approximately negligible and the flow develops against a stable background stratification, the ABL is considered conventionally neutral (CNBL, Zilitinkevich and Esau 2002). CNBLs are commonly observed, for example, over sea, above large lakes, and over land during the transition period after sunset or on cloudy days with powerful winds (Allaerts and Meyers 2017; Liu and Stevens 2022)

For simplicity, we neglect the effects of baroclinicity, clouds, subsidence, and nonstationarity and focus on the Northern Hemisphere, where the Coriolis parameter  $f > 0$ . Then, it follows from dimensional analysis that the dynamics in CNBLs are governed by two independent dimensionless parameters, e.g. the Rossby number  $Ro = u_*/(fz_0)$  and the Zilitinkevich number  $Zi = N/f$  (Esau 2004), where  $u_*$  is the friction velocity,  $z_0$  is the roughness length, and  $N$  is the free-atmosphere Brunt-Väisälä frequency. Note that the ratio  $N/f$  is sometimes called the inverse Prandtl ratio (Dritschel and McKiver 2015) and is closely related to the square root of the slope Burger number (Shapiro and Fedorovich 2008). In this study, the coordinate system is oriented such that the streamwise direction is parallel to the wind direction at the surface, and the spanwise direction is orthogonal to the streamwise and vertical directions. Thus, the geostrophic drag law (GDL) for CNBLs can be written as (e.g. Zilitinkevich and Esau 2005; Liu et al. 2021a),

$$A(Zi) = \ln Ro - \frac{\kappa U_g}{u_*}, \quad (1a)$$

$$B(Zi) = -\frac{\kappa V_g}{u_*}, \quad (1b)$$

where  $\kappa = 0.4$  is the von Kármán constant,  $A$  and  $B$  are the GDL coefficients<sup>1</sup>, and  $(U_g, V_g)$  are the streamwise and spanwise components of the geostrophic wind. If the expressions of  $A$  and  $B$  are already known, the geostrophic drag coefficient  $u_*/(U_g^2 + V_g^2)^{1/2}$  and the cross-isobaric angle  $\alpha_0 = \arctan(|V_g/U_g|)$  can be determined from Eq. (1).

In general, the GDL coefficients  $A$  and  $B$  can be parameterized through two approaches. One is by first parameterizing the eddy viscosity (Ellison 1955; Krishna 1980; Kadantsev et al. 2021), and the other is by first parameterizing the mean wind velocity (Zilitinkevich 1989b,a; Zilitinkevich et al. 1998; Narasimhan et al. 2024). Then, an asymptotic matching technique is used to determine the final expressions of the GDL coefficients  $A$  and  $B$ . For

<sup>1</sup> Note that the GDL coefficients  $A$  and  $B$  defined by Eq. (1) are identical to  $\tilde{A}$  and  $\tilde{B}$  (but different from  $A$  and  $B$ ) in Zilitinkevich and Esau (2005). For the relation between  $(\tilde{A}, \tilde{B})$  and  $(A, B)$  please refer to Eq. (9) in Zilitinkevich and Esau (2005).

63 example, [Ellison \(1955\)](#) derived analytical expressions for  $A$  and  $B$  by solving  
 64 the Ekman equations under the assumption of a linear eddy viscosity profile  
 65 throughout the boundary layer. [Zilitinkevich \(1989b,a\)](#) used log-polynomial  
 66 approximations for the wind and temperature profiles in combination with the  
 67 requirement that these are asymptotically consistent with the well-established  
 68 Monin-Obukhov surface-layer flux-profile relationships to obtain the GDL and  
 69 heat transfer laws for stable ABLs. [Zilitinkevich et al. \(1998\)](#) extended the  
 70 ideas of [Zilitinkevich \(1989b,a\)](#) to account for the effect of static stability in  
 71 the free flow above the ABL. They expressed the GDL coefficients  $A$  and  $B$   
 72 with composite stability parameters, which are constructed through the in-  
 73 terpolation between the Ekman length scale  $L_f = u_*/f$  ([Ekman 1905](#)), the  
 74 external static-stability length scale  $L_n = u_*/N$  ([Kitaigorodskii and Joffre](#)  
 75 [1988](#)), and the Obukhov length scale  $L_s = -u_*^3/(\kappa\beta q_s)$  ([Obukhov 1946](#)) with  
 76  $q_s$  denoting the surface heat flux and  $\beta = g/\theta_0$  the buoyancy parameter. **Here,**  
 77  $g$  is the gravity acceleration and  $\theta_0$  is the reference potential temperature.  
 78 Later, [Zilitinkevich and Esau \(2005\)](#) proposed the general expressions of the  
 79 coefficients  $A$  and  $B$  for stable ABLs and CNBLs,

$$A = -am_A + \ln(a_0 + m_A) - \ln\left(\frac{fh}{u_*}\right), \quad (2a)$$

$$B = \frac{fh}{u_*}(b_0 + bm_B^2). \quad (2b)$$

80 Here  $(a, a_0, b, b_0)$  are empirical constants, and  $(m_A, m_B)$  are the composite  
 81 stratification parameters for the coefficients  $(A, B)$ , respectively,

$$\frac{m_A^2}{h^2} = \frac{1}{L_s^2} + \frac{c_{na}^2}{L_n^2} + \frac{c_{fa}^2}{L_f^2}, \quad (3a)$$

$$\frac{m_B^2}{h^2} = \frac{1}{L_s^2} + \frac{c_{nb}^2}{L_n^2} + \frac{c_{fb}^2}{L_f^2}, \quad (3b)$$

82 where  $(c_{fa}, c_{fb}, c_{na}, c_{nb})$  are empirical constants.

83 To obtain analytic expressions for  $A$  and  $B$ , the boundary-layer height  
 84  $h$  in Eqs. (2) and (3) has to be parameterized. In general, two ABL-depth  
 85 scales were proposed for the ABL dominated by the static stability aloft:  
 86 one is  $h \propto u_*/\sqrt{Nf}$  ([Pollard et al. 1973](#)), and the other is  $h \propto u_*/N$  ([Ki-](#)  
 87 [taigorodskii and Joffre 1988](#)). Using energy considerations, [Zilitinkevich and](#)  
 88 [Mironov \(1996\)](#) developed a simple equation for the equilibrium height of the  
 89 stable ABLs, and gave a comprehensive discussion of the CNBL-depth scales.  
 90 In particular, they advocated the scale  $u_*/N = L_n$ , where the ABL depth  
 91 ceases to depend on the Coriolis parameter if the static stability is sufficiently  
 92 strong. Note that this scaling has also been demonstrated by [Pedersen et al.](#)  
 93 [\(2014\)](#) using large eddy simulations (LES). Using momentum considerations,  
 94 [Zilitinkevich et al. \(2002\)](#) advocated the scale  $u_*/\sqrt{Nf}$ , where the ABL depth  
 95 depends on the Coriolis parameter regardless of the strength of static stability.  
 96 [Mironov and Fedorovich \(2010\)](#) revisited this problem and obtained a more

97 general power-law formulation for the CNBL depth, viz.,  $h/L_n \propto (N/f)^\delta$ ,  
 98 where  $\delta$  is the exponent. With  $\delta = 0$  and  $\delta = 1/2$ , the formulations by [Ki-](#)  
 99 [taigorodskii and Joffre \(1988\)](#) and by [Pollard et al. \(1973\)](#), respectively, are  
 100 recovered. However, as convincingly argued by [Mironov and Fedorovich \(2010\)](#),  
 101  $\delta$  can assume any value in the range  $0 \leq \delta < 1$ . Importantly,  $\delta$  cannot be deter-  
 102 mined by dimensional analysis. An exact solution to the problem in question  
 103 is needed, which is still an active research topic. For example, [Zilitinkevich](#)  
 104 [et al. \(2007, 2012\)](#) usually parameterized the boundary-layer height  $h$  as

$$\frac{L_f^2}{h^2} = \frac{1}{c_r^2} + \frac{Zi}{c_n^2} + \frac{\mu}{c_s^2}, \quad (4)$$

105 where  $(c_r, c_n, c_s)$  are empirical constants and  $\mu = L_f/L_s$  is the Kazanski-  
 106 Monin parameter ([Kazanski and Monin 1961](#)). Note that for CNBLs Eq. (4)  
 107 has been well validated against simulations ([Liu et al. 2021a](#)) and field mea-  
 108 surement data ([Uttal et al. 2002](#); [Zilitinkevich and Esau 2009](#)).

109 The  $A$  and  $B$  coefficients from the GDL play a critical role in estimat-  
 110 ing available wind resources at higher altitudes through vertical extrapolation  
 111 ([Gryning et al. 2007](#); [Kelly and Gryning 2010](#); [Kelly and Troen 2016](#)) or at dif-  
 112 ferent sites through horizontal extrapolation ([Troen and Petersen 1989](#); [Kelly](#)  
 113 [and Jørgensen 2017](#)), and in predicting the turbulent flows over wind farms  
 114 ([Li et al. 2022](#)) and canopies. [Liu et al. \(2021a\)](#) numerically revisited the ana-  
 115 lytical expressions of  $A$  and  $B$  for CNBLs proposed by [Zilitinkevich and Esau](#)  
 116 [\(2005\)](#). As they found significant deviations between the simulation results and  
 117 the original parameterization of the GDL, the authors updated the empirical  
 118 constants involved in Eqs. (2)-(4). In their simulations, only the free atmo-  
 119 spheric lapse rate and latitude were varied, and thus only a limited range of  
 120 the geostrophic drag coefficient was covered. [Liu et al. \(2021b\)](#) performed sim-  
 121 ulations by varying the lapse rate and roughness length, but they considered  
 122 only six cases and didn't investigate the GDL. To further evaluate the validity  
 123 of the GDL, systematic simulations that cover a wide range of atmospheric  
 124 parameters are required, which we provide in this study.

125 The GDL parameterization of Eqs. (2)-(4) has a relatively complicated  
 126 form, which includes ten empirical constants for CNBLs. This poses significant  
 127 challenges in determining the values of these empirical constants. For example,  
 128 [Liu et al. \(2021a\)](#) had to empirically determine the values for  $a$  and  $b$  such  
 129 that the asymptotic behavior of  $A$  and  $B$  is well captured in the high  $Zi$  limit,  
 130 and the correction constants  $a_0$  and  $b_0$  are set such that  $A$  and  $B$  also capture  
 131 the low  $Zi$  limit well. Although this approach sometimes works, it is difficult  
 132 to adapt to other flow configurations, such as wind farms or canopy flows, as  
 133 it requires a lot of data and is technically challenging. As a compromise, [Li](#)  
 134 [et al. \(2022\)](#) had to resort to numerically fitting the GDL coefficients instead  
 135 of analytically updating the GDL to wind farm flows. Therefore, it is necessary  
 136 to further investigate the GDL for CNBLs theoretically.

137 The organization of the paper is as follows. In Sect. 2 we derive analytical  
 138 expressions of  $A$  and  $B$ . In Sect. 3 we discuss the numerical method and LES

139 setup for CNBLs, which covers a much wider range of  $u_*/G$  than considered  
 140 previously. In Sect. 4 we validate the derived expressions of  $A$  and  $B$  with the  
 141 simulation data. In Sect. 5 we compare the geostrophic drag coefficient and the  
 142 cross-isobaric angle obtained from the simulations and theoretical predictions.  
 143 We conclude with a summary of the main findings in Sect. 6.

## 144 2 Theoretical model

### 145 2.1 Parametrization of the boundary-layer height

146 In this study, we use the boundary layer height parametrization proposed by  
 147 Pollard et al. (1973). We adopt this parametrization as it is derived from  
 148 momentum considerations, which also form the basis of the GDL derivation.  
 149 Therefore, we parameterize the boundary-layer depth as

$$\frac{h}{L_n} = c_n \sqrt{Zi}, \quad (5)$$

150 where the constant  $c_n = 2^{3/4}$  is determined theoretically by Pollard et al.  
 151 (1973). Note that Eq. (5) is an asymptotic case of Eq. (4) since the middle  
 152 term of Eq. (4) becomes the dominant one for  $Zi \gg 1$ .

### 153 2.2 Analytical expression of $A$

154 We first determine the expression of  $A$ . In the surface layer, the mean stream-  
 155 wise velocity  $U$  can be written as

$$\frac{\kappa U}{u_*} = \ln \left( \frac{z}{z_0} \right). \quad (6)$$

156 Above the surface layer, Zilitinkevich and Esau (2005) assumed the streamwise  
 157 velocity gradient scales as  $N$ ,

$$\frac{1}{N} \frac{dU}{dz} = \frac{1}{\kappa} f_u(\xi), \quad \xi = \frac{z}{h}, \quad (7)$$

158 where  $f_u$  is presumed to be independent of  $Ro$  and  $Zi$ . We remark that Liu  
 159 and Stevens (2022) derived an analytical expression of  $U$  that is valid in the  
 160 entire boundary layer, which indicates that  $f_u$  is independent of  $Ro$ . However,  
 161 the independence of  $f_u$  from  $Zi$  is only valid asymptotically when  $Zi \gg 1$ .  
 162 Despite this, we continue to use Eq. (7) to derive the analytical expression for  
 163  $A$ , evaluating its performance for  $Zi \gg 1$ .

164 Integrating Eq. (7) from a height  $z$  to the top of the boundary layer, we  
 165 find

$$\frac{\kappa}{u_*} [U_g - U(z)] = \frac{h}{L_n} \int_{\xi}^1 f_u d\xi'. \quad (8)$$

166 We further assume the mean streamwise velocity given by Eqs. (6) and (8)  
 167 matches at some height  $\xi = L_n/(c_1 h)$ , where  $c_1$  is an empirical constant.  
 168 Thus, by substituting Eq. (6) into Eq. (8), there is

$$\frac{\kappa U_g}{u_*} = \ln \left( \frac{L_n}{c_1 z_0} \right) + \frac{h}{L_n} \int_{\frac{L_n}{c_1 h}}^1 f_u d\xi'. \quad (9)$$

169 Finally, substituting Eqs. (1a) and (5) into Eq. (9) and noting that  $L_f/L_n =$   
 170  $Zi$ , we obtain

$$A = \ln(c_1 Zi) - a_1 \sqrt{Zi}, \quad (10)$$

171 where  $a_1 = c_n \int_{\frac{L_n}{c_1 c_n \sqrt{Zi}}}^1 f_u d\xi'$ . Although  $a_1$  may depend slightly on  $Zi$ , we  
 172 assume it to be constant for simplicity. **Note that the assumption of constant**  
 173  **$a_1$  implies that  $U_g/(hN)$  retains a  $Zi$ -dependence.**

174 We remark that, Eq. (10) is the same as the first expression of Eq. (39) in  
 175 Zilitinkevich and Esau (2005), which is an asymptotic expression correspond-  
 176 ing to  $Zi \gg 1$ . Due to its relatively simple form, the performance of Eq. (10) at  
 177 both moderate and high values of  $Zi$  is evaluated below. In addition, by sub-  
 178 stituting Eq. (5) into Eq. (2a), we get  $A = \ln(c_{na} Zi) - ac_{na} c_n \sqrt{Zi}$  in the limit  
 179  $Zi \gg 1$ , which is the same as Eq. (10) when  $c_{na} = c_1$  and  $ac_{na} c_n = a_1$ . This  
 180 indicates that the introduction of the correction constant  $a_0$  is not unnecessary  
 181 for CNBLs.

## 182 2.3 Analytical expression of $B$

183 To determine the analytical expression of  $B$ , we recall that

$$\frac{d\tau_y}{dz} = f(U - U_g), \quad (11)$$

184 where  $\tau_y$  is the spanwise component of the total shear stress tensor. First, we  
 185 focus on the surface layer. Then, by substituting Eq. (6) into Eq. (11) and  
 186 combining the result with Eq. (1a) there is

$$\frac{\kappa}{f u_*} \frac{d\tau_y}{dz} = A + \ln \left( \frac{z}{L_f} \right). \quad (12)$$

187 The bottom boundary condition of Eq. (12) is  $\tau_y(0) = 0$ . Integrating Eq. (12)  
 188 from 0 to  $z$ , one can obtain

$$\frac{\kappa \tau_y}{f u_*} = \left[ A - 1 + \ln \left( \frac{z}{L_f} \right) \right] z. \quad (13)$$

189 In the surface layer the eddy viscosity approach is valid, such that

$$\tau_y = K_m \frac{dV}{dz}, \quad K_m = \kappa u_* z, \quad (14)$$

190 where  $V$  is the spanwise velocity. By combining Eqs. (13) and (14), there is

$$\frac{\kappa^2}{f} \frac{dV}{dz} = A - 1 + \ln\left(\frac{z}{L_f}\right). \quad (15)$$

191 The bottom boundary condition of Eq. (15) is  $V(0) = 0$ . Then, by integrating  
192 Eq. (15) from 0 to  $z$  one can determine the mean spanwise velocity  $V$  in the  
193 surface layer as

$$\frac{\kappa^2 V}{f} = \left[ A - 2 + \ln\left(\frac{z}{L_f}\right) \right] z. \quad (16)$$

194 Next, similar to the derivation of  $A$ , we also assume the spanwise velocity  
195 gradient scales as  $N$ ,

$$\frac{1}{N} \frac{dV}{dz} = -\frac{1}{\kappa} f_v(\xi), \quad (17)$$

196 where  $f_v$  is independent of  $Ro$  and  $Zi$ . Integrating Eq. (17) from a height  $z$  to  
197 the top of the boundary layer, there is

$$\frac{\kappa}{u_*} (V_g - V) = -\frac{h}{L_n} \int_{\xi}^1 f_v d\xi'. \quad (18)$$

198 We further assume the mean spanwise velocity given by Eqs. (16) and (18)  
199 matches at the height  $\xi = L_n/(c_2 h)$ , where  $c_2$  is an empirical constant. Thus,  
200 by substituting Eq. (16) into Eq. (18), we find

$$\frac{\kappa V_g}{u_*} = \frac{L_n}{\kappa c_2 L_f} \left[ A - 2 + \ln\left(\frac{L_n}{c_2 L_f}\right) \right] - \frac{h}{L_n} \int_{\frac{L_n}{c_2 h}}^1 f_v d\xi'. \quad (19)$$

201 Finally, substituting Eqs. (1b), (5) and (10) into Eq. (19) and noting that  
202  $L_f/L_n = Zi$ , we find

$$B = \frac{2 + \ln(c_2/c_1)}{\kappa c_2 Zi} + \frac{a_1}{\kappa c_2 \sqrt{Zi}} + b_1 \sqrt{Zi}, \quad (20)$$

203 where  $b_1 = c_n \int_{\frac{1}{c_2 c_n \sqrt{Zi}}}^1 f_v d\xi'$ . Similar to  $a_1$ , we assume  $b_1$  to be constant.

204 We remark that, Eq. (20) is different from the second expression of Eq. (39)  
205 in Zilitinkevich and Esau (2005). In the derivation of Zilitinkevich and Esau  
206 (2005) the spanwise velocity is not continuous across different layers. As a  
207 result, their conclusion includes only the final term of Eq. (20), while the first  
208 two terms are omitted. As shown below, the prediction of Zilitinkevich and  
209 Esau (2005) with only the final term of Eq. (20) leads to significant deviations  
210 at moderate values of  $Zi$ . On the other hand, by substituting Eq. (5) into  
211 Eq. (2b), we find that  $B = b_0 c_n / \sqrt{Zi} + b c_{nb}^2 c_n^3 \sqrt{Zi}$  in the limit  $Zi \gg 1$ .  
212 Meanwhile, in the limit  $Zi \gg 1$  the  $1/Zi$  term in Eq. (20) will be smallest and  
213 thus Eq. (20) can be approximated as  $B = a_1 / (\kappa c_2 \sqrt{Zi}) + b_1 \sqrt{Zi}$ . Clearly,  
214 these two expressions are the same when  $b_0 c_n = a_1 / (\kappa c_2)$  and  $b c_{nb}^2 c_n^3 = b_1$ .  
215 This indicates that the introduction of the correction constant  $b_0$  in Eq. (2b)  
216 is to improve the prediction of  $B$  using Eq. (2b) at moderate values of  $Zi$ .

### 217 3 Large-eddy simulation

218 Using state-of-the-art LES, Liu et al. (2021a) simulated the CNBL flow over an  
 219 infinite flat surface with homogeneous roughness. These simulations are used  
 220 to determine the empirical constants in the original GDL parameterization  
 221 of Zilitinkevich and Esau (2005). However, in that study only the free atmo-  
 222 spheric lapse rate and the latitude were varied, and thus only a very narrow  
 223 range of the geostrophic drag coefficient ( $u_*/G$ ) was covered. To evaluate the  
 224 validity of the GDL in practical applications, extended simulations that cover  
 225 a wide range of atmospheric parameters are required. Therefore, we perform 19  
 226 new LES in which we vary the free-atmosphere lapse rate ( $\Gamma$ ), the latitude ( $\phi$ ),  
 227 the geostrophic wind speed ( $G$ ), and the roughness length ( $z_0$ ). This extends  
 228 the range of  $u_*/G$  in simulations from  $[0.019, 0.026]$  up to  $[0.019, 0.047]$ , which  
 229 covers about half of commonly observed values in atmospheric measurements  
 230 (Hess and Garratt 2002a,b; van der Laan et al. 2020).

231 The code used to solving the flow field is the same as that adopted by Liu  
 232 et al. (2021a), which originates from the work by Albertson (1996), and later  
 233 contributions by Bou-Zeid et al. (2005), Calaf et al. (2010), and many oth-  
 234 ers. The grid points are uniformly distributed, and the computational planes  
 235 for horizontal and vertical velocities are staggered in the vertical direction. A  
 236 second-order finite difference method is used in the vertical direction, while a  
 237 pseudo-spectral discretization with periodic boundary conditions is employed  
 238 in the horizontal directions. Time integration is performed using the second-  
 239 order Adams-Bashforth method (Canuto et al. 1988). The projection method is  
 240 used to ensure the divergence-free condition of the velocity field (Chorin 1968).  
 241 At the top boundary the vertical velocity, the sub-grid scale shear stress and  
 242 potential temperature flux are enforced to zero, while the potential tempera-  
 243 ture gradient is imposed by a constant value. In the top 25% of the domain a  
 244 Rayleigh damping layer is used to reduce the effects of gravity waves (Klemp  
 245 and Lilly 1978). At the bottom boundary, we employ a wall model based on  
 246 the Monin-Obukhov similarity theory for both the velocity and potential tem-  
 247 perature fields (Moeng 1984; Stoll and Porté-Agel 2008).

248 Similar to Liu et al. (2021a), the computational domain size is  $2\pi$  km  $\times$   
 249  $2\pi$  km  $\times$  2 km in streamwise, spanwise, and vertical directions, respectively,  
 250 and the corresponding grid points are  $288 \times 288 \times 281$ . Pedersen et al. (2014)  
 251 demonstrated that for CNBLs convergence is obtained in much coarser meshes  
 252 than required for stable boundary layer simulations. In our previous work (Liu  
 253 et al. 2021a,b) we studied grid convergence and obtained similar conclusions,  
 254 showing that the employed grid resolution used here is sufficient. The horizon-  
 255 tal domain size is at least six times larger than the boundary layer height such  
 256 that long streamwise structures are captured appropriately for all cases. The  
 257 initial potential temperature profile is  $\theta(z) = \theta_0 + \Gamma z$ , where  $\theta_0 = 300$  K and  
 258  $\Gamma = 0.001 \sim 0.009$  K m<sup>-1</sup>. The initial velocity profile is set as the geostrophic  
 259 wind  $G = 6 \sim 20$  m s<sup>-1</sup>. The latitude is  $\phi = 10 \sim 50^\circ$  and the roughness  
 260 length is  $z_0 = 0.0007 \sim 0.32$  m. To reduce the impact of inertial oscillations,  
 261 we run the simulations for a long duration with respect to the Coriolis param-

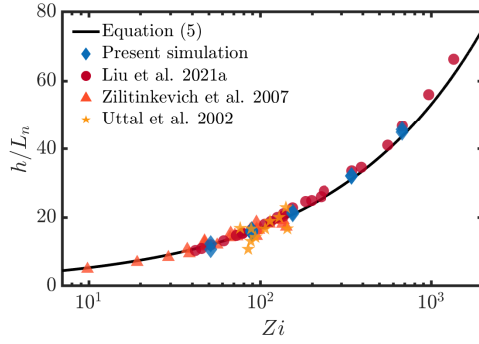


**Table 1** The table summarizes the present simulations.

Case no.	$\Gamma$ (K m <sup>-1</sup> )	$\phi$ (deg)	$G$ (m s <sup>-1</sup> )	$z_0$ (m)	$\alpha_0$ (deg)	$u_*$ (m s <sup>-1</sup> )	$h$ (m)	$A$	$B$
1	0.001	50	6	0.09	21.7	0.265	498	1.77	3.34
2	0.001	50	20	0.04	16.4	0.751	1626	1.81	3.01
3	0.003	50	6	0.09	24.0	0.263	412	1.84	3.72
4	0.003	50	6	0.18	25.5	0.281	440	1.83	3.68
5	0.003	50	10	0.04	20.5	0.392	636	1.82	3.57
6	0.003	50	12	0.001	15.3	0.352	583	1.82	3.59
7	0.003	50	12	0.01	17.8	0.416	681	1.84	3.53
8	0.003	50	12	0.02	19.0	0.439	712	1.85	3.57
9	0.003	50	12	0.1	21.7	0.504	818	1.87	3.52
10	0.003	50	16	0.004	16.1	0.512	846	1.93	3.47
11	0.003	50	20	0.0007	14.3	0.557	924	1.86	3.56
12	0.003	50	20	0.04	18.8	0.745	1218	1.86	3.45
13	0.003	50	20	0.32	22.6	0.890	1440	1.82	3.45
14	0.009	50	6	0.09	27.7	0.258	324	1.91	4.33
15	0.009	50	20	0.04	22.6	0.736	910	1.97	4.17
16	0.009	20	8	0.09	32.4	0.294	555	1.91	5.83
17	0.009	20	16	0.01	26.3	0.487	908	2.00	5.82
18	0.009	10	8	0.09	38.9	0.255	677	1.87	7.88
19	0.009	10	16	0.01	32.3	0.432	1128	1.85	7.92

eter. As shown in Liu et al. (2021a), friction velocity and cross-isobaric angle show very limited oscillations when the dimensionless time  $ft > 9$ , which is consistent with the conclusion of Pedersen et al. (2014) that the mean momentum equations reach a steady state balance after  $ft > 6$ . Furthermore, we note that in Liu et al. (2021a) we averaged over a time span  $\Delta(ft) = 1$ , while in Liu et al. (2021b) we averaged over  $\Delta(ft) = 2\pi$ . The comparison of these data in figures 4 and 5 below demonstrates that the inertial oscillations has been significantly damped. Therefore, statistics are collected over the interval  $ft \in [9, 10]$ , where the boundary layer has reached a quasi-stationary state. A summary of these simulations is given in Table 1, where  $G = (U_g^2 + V_g^2)^{1/2}$  is the geostrophic wind speed,  $\alpha_0 = \arctan(|V_g/U_g|)$  is the cross-isobaric angle (i.e. the total wind angle change across the boundary layer), and  $h$  is the boundary layer height.

It is worth noting that the boundary layer height can be defined based on the vertical profiles of total turbulent stress, wind speed, potential temperature flux, or potential temperature (Abkar and Porté-Agel 2013; Allaerts and Meyers 2015; Kelly et al. 2019). For example, one of the commonly accepted definitions of the boundary layer height is  $h_{0.05}$ , which is defined as the height where the total turbulent stress is 5% of its wall value. In this study, we also define the boundary layer height  $h$  based on the vertical profile of total turbulent stress. However, since the total shear stress follows a power law with exponent  $3/2$  (Nieuwstadt 1984), a more appropriate definition of the boundary-layer height is  $h = h_{0.05}/(1 - 0.05^{2/3})$ , which is the height where the total turbulent stress first reduces to zero (van Dop and Axelsen 2007; Liu et al. 2021b).



**Fig. 1** The dimensionless boundary-layer height  $h/L_n$  versus the Zilitinkevich number  $Zi$ . Solid line: theoretical curve by Eq. (5) with  $c_n = 2^{3/4}$ ; diamonds: simulation data of Table 1; circles: simulation data of Liu et al. (2021a); triangles: simulation data of Zilitinkevich et al. (2007); squares: atmospheric data of Uttal et al. (2002).

## 286 4 Model validation

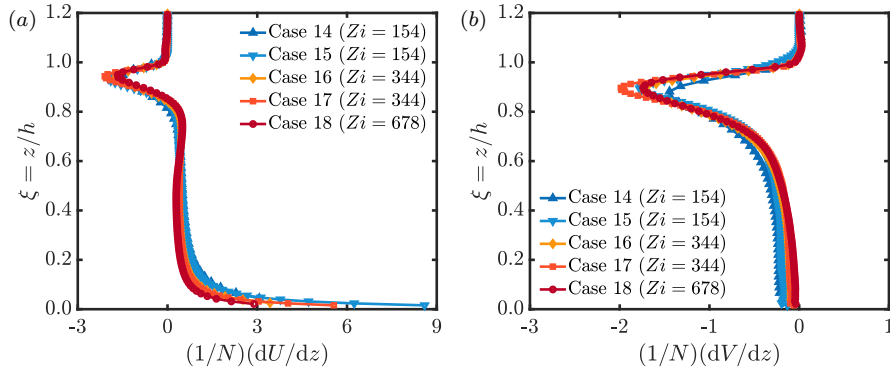
### 287 4.1 The boundary-layer height and wind gradients

288 Figure 1 compares the dimensionless boundary-layer height  $h/L_n$  obtained  
 289 from atmospheric measurements (Uttal et al. 2002), numerical simulations  
 290 (Zilitinkevich et al. 2007; Liu et al. 2021a), and theoretical predictions. The  
 291 good agreement confirms that the boundary-layer height  $h$  is indeed parame-  
 292 terized well by Eq. (5). Since  $Zi = N/f$  and  $L_n = u_*/N$ , Eq. (5) also indicates  
 293 that  $h/(u_*/\sqrt{Nf}) = c_n$ , i.e. the boundary-layer height  $h$  scales as  $u_*/\sqrt{Nf}$ .  
 294 This result is in agreement with Pedersen et al. (2014), who demonstrated  
 295 that the scaling of the boundary layer height with  $Zi$  remains constant over  
 296 time after reaching the statistically stationary state ( $ft > 6$ ).

297 Figure 2 shows the profiles of normalized vertical gradient of (a) streamwise  
 298 velocity  $(1/N)(dU/dz)$  and (b) spanwise velocity  $(1/N)(dV/dz)$  in CNBLs for  
 299 large values of  $Zi$ . The good collapse of all symbols indicates that the wind  
 300 gradients indeed scale as  $N$  for  $Zi \gg 1$ . Note that the asymptotic independence  
 301 of  $f_u$  on  $Zi$  is valid  $\xi \gtrsim 0.2$  due to the term proportional to  $1/\xi$  involved in  
 302  $f_u$  (see Figure 2a). In contrast, the asymptotic independence of  $f_v$  on  $Zi$  is  
 303 nearly valid in the whole boundary layer (see Figure 2b).

### 304 4.2 The coefficients $A$ and $B$

305 Figure 3 shows the comparison of the GDL coefficients  $A$  and  $B$  obtained from  
 306 the simulations (symbols, see Table 1 and Liu et al. (2021a)), the theoretical  
 307 predictions of (a) Eq. (10) and (b) Eq. (20) (solid line), and the theoretical  
 308 prediction of Zilitinkevich and Esau (2005), i.e. the final term in Eq. (20)  
 309 (dashed line). The empirical constants  $a_1 = 0.12$ ,  $b_1 = 0.29$ ,  $c_1 = 0.24$ ,  $c_2 =$   
 310  $0.054$  are determined from the simulation data of Liu et al. (2021a) using a



**Fig. 2** The profiles of normalized vertical gradient of (a) streamwise velocity  $(1/N)(dU/dz)$  and (b) spanwise velocity  $(1/N)(dV/dz)$  in CNBLs. For case information see Table 1.

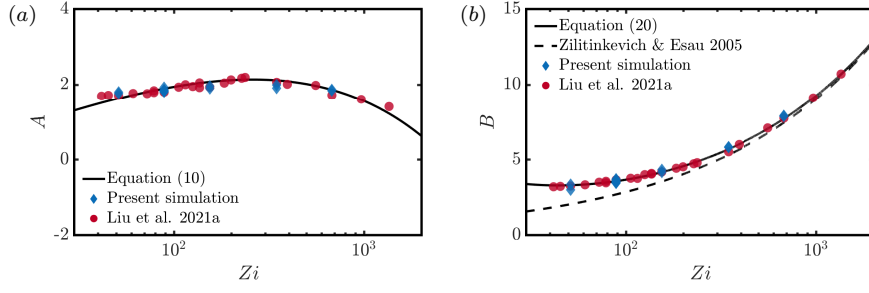
311 least-squares fitting procedure (e.g. the MATLAB `fminsearch` function). To  
 312 evaluate the goodness of the fit, we introduce the mean absolute percentage  
 313 error (MAPE),

$$\text{MAPE}(X) = 100 \frac{1}{n} \sum_{i=1}^n \left| \frac{X_i^{\text{LES}} - X_i^{\text{fit}}}{X_i^{\text{LES}}} \right|, \quad X = A, B, \quad (21)$$

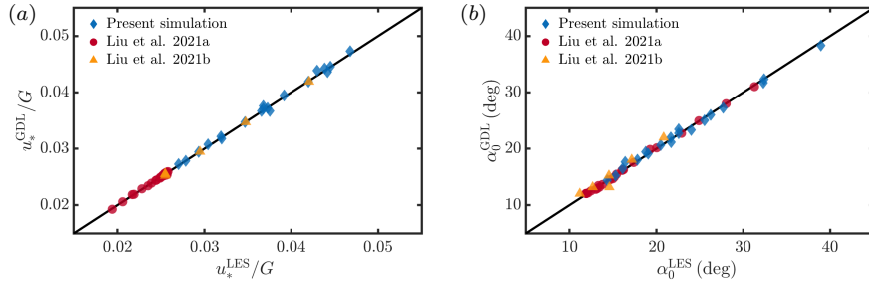
314 where  $i$  is the case number,  $n = 24$  is the total number of the simulations  
 315 performed by Liu et al. (2021a), and the superscripts “LES” and “fit” de-  
 316 note the values of  $X$  obtained by LES and the fitting procedure. We find that  
 317  $\text{MAPE}(A) = 3.9$  and  $\text{MAPE}(B) = 1.3$ , indicating the goodness of the fit.  
 318 Overall, the present theoretical predictions capture the simulation results of  
 319 Liu et al. (2021a) and the present study very well. This confirms the validity  
 320 of the simplified analytical expressions of  $A$  and  $B$  given by Eqs. (10) and  
 321 (20), which have much less empirical constants than Eq. (2) proposed by Zil-  
 322 itinkevich and Esau (2005). Note that Figure 3b also shows clearly that the  
 323 predictions of Zilitinkevich and Esau (2005) underestimates significantly the  
 324 values of  $B$  at moderate values of  $Zi \lesssim 300$ .

## 325 5 Geostrophic drag coefficient and cross-isobaric angle

326 Figure 4 compares (a) the geostrophic drag coefficient  $u_*/G$  and (b) the cross-  
 327 isobaric angle  $\alpha_0 = \arctan(|V_g/U_g|)$  obtained from the present simulations of  
 328 Table 1 and the previous simulations of Liu et al. (2021a,b) with that from  
 329 the GDL given by Eq. (1), where the GDL coefficients  $A$  and  $B$  are parame-  
 330 terized by Eqs. (10) and (20), respectively. Note that the empirical constants  
 331  $(a_1, b_1, c_1, c_2)$  involved in Eqs. (10) and (20) are determined merely based on  
 332 the simulation data of Liu et al. (2021a), where  $u_*/G$  covers only a narrow  
 333 range of  $u_*/G \in [0.019, 0.026]$ . The figure shows that the agreement between  
 334 the simplified parametrization and all the numerical data with a wide range of



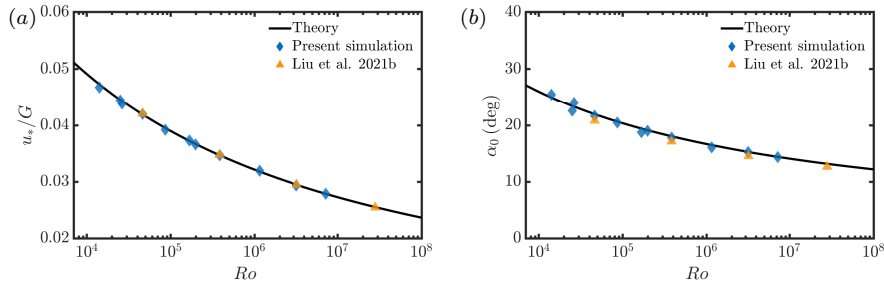
**Fig. 3** The GDL coefficients (a)  $A$  and (b)  $B$  versus the Zilitinkevich number  $Z_i$ . Solid line: theoretical curve of (a) Eq. (10) and (b) Eq. (20) with  $a_1 = 0.12, b_1 = 0.29, c_1 = 0.24, c_2 = 0.054$  determined using a least-squares fitting procedure with the simulation data of Liu et al. (2021a); dashed line: theoretical curve of Zilitinkevich and Esau (2005), i.e. Eq. (20) with only the final term; diamonds: present simulations of Table 1; circles: previous simulations of Liu et al. (2021a).



**Fig. 4** The comparison of (a) the geostrophic drag coefficient  $u_*/G$  and (b) the cross-isobaric angle  $\alpha_0 = \arctan |V_g/U_g|$  obtained from various simulation data and the GDL of Eq. (1) with  $A$  and  $B$  parameterized by Eqs. (10) and (20). Diamonds: present simulations of Table 1; circles: previous simulations of Liu et al. (2021a); triangles: previous simulations of Liu et al. (2021b). Note that the empirical constants involved in Eqs. (10) and (20) are determined only from the simulation data of Liu et al. (2021a) with a limited range of  $u_*/G$ .

335  $u_*/G \in [0.019, 0.047]$  is very good. In particular, figure 4a shows that the range  
 336 of  $u_*/G$  of the simulations of Liu et al. (2021a) is between 0.019 and 0.026,  
 337 while that of the present simulations of Table 1 is between 0.028 and 0.047.  
 338 These simulations together cover the values of  $u_*/G$  commonly observed in  
 339 atmospheric measurements (Hess and Garratt 2002a,b), and the good agree-  
 340 ment between the theoretical predictions and simulations of Liu et al. (2021b)  
 341 and the present study confirms the validity of the GDL for CNBLs in the high  
 342 geostrophic drag coefficient regime. Figure 4b shows that the cross-isobaric  
 343 angle varies between  $10^\circ$  and  $40^\circ$ , where all LES data collapse to the theoret-  
 344 ical curve. This good agreement is expected as  $\alpha_0 = \arcsin [(Bu_*)/(\kappa G)]$  and  
 345  $B$  (figure 3b) and  $u_*/G$  (figure 4a) have already been predicted accurately.

346 Figure 5 shows (a) the geostrophic drag coefficient  $u_*/G$  and (b) the cross-  
 347 isobaric angle  $\alpha_0 = \arctan (|V_g/U_g|)$  versus the Rossby number  $Ro = u_*/(fz_0)$ .  
 348 The solid line is the theoretical predictions of Eq. (1) with  $A$  and  $B$  param-



**Fig. 5** The (a) geostrophic drag coefficient  $u_*/G$  and (b) cross-isobaric angle  $\alpha_0 = \arctan(|V_g/U_g|)$  versus the Rossby number  $Ro$  for the cases with the Zilitinkevich number  $Zi = 89$ . Solid line: theoretical predictions of Eq. (1) with  $A$  and  $B$  parameterized by Eqs. (10) and (20); diamonds: present simulations of Table 1; triangles: previous simulations of Liu et al. (2021b). Note that the empirical constants involved in Eqs. (10) and (20) are determined only from the simulation data of Liu et al. (2021a) with a limited range of  $u_*/G$ .

349 eterized by Eqs. (10) and (20), the diamonds are the simulations of Table 1,  
 350 and the triangles are the simulation of Liu et al. (2021b). The figure focuses  
 351 on cases with a fixed Zilitinkevich number ( $Zi = 89$ ), which is a typical value  
 352 observed in atmospheric measurements (see Figure 1). In particular, the fig-  
 353 ure focuses on cases with the lapse rate  $\Gamma = 0.003 \text{ K m}^{-1}$  and the latitude  
 354  $\phi = 50^\circ$ . The figure shows that the geostrophic drag coefficient  $u_*/G$  and the  
 355 cross-isobaric angle  $\alpha_0$  decrease as the Rossby number  $Ro$  increases, by either  
 356 increasing the geostrophic wind speed  $G$  or decreasing the roughness length  
 357  $z_0$  (Table 1). The collapse of all symbols to a single curve, which can be ac-  
 358 curately predicted by the GDL of Eq. (1), clearly demonstrates the validity  
 359 of the simplified parametrization. Note that the empirical constants involved  
 360 in Eqs. (10) and (20) are determined only from the simulation data of Liu  
 361 et al. (2021a) with a limited range of  $u_*/G$ . Therefore, figure 5 also indicates  
 362 that the GDL is very useful in predicting the geostrophic drag coefficient and  
 363 cross-isobaric angle in the relevant meteorological regime (Hess and Garratt  
 364 2002a,b).

## 365 6 Conclusions

366 We investigated theoretically and numerically the GDL for CNBLs. First, we  
 367 derived the analytical expressions of  $A$  and  $B$  based on two assumptions. That  
 368 is, the eddy viscosity approach  $K_m = \kappa u_* z$  is valid in the surface layer, and the  
 369 wind gradients normalized by the free-atmosphere Brunt-Väisälä frequency  
 370  $N$  have universal profiles above the surface layer. The validity of the first  
 371 assumption is self-evident, while our physical arguments and simulation data  
 372 support the second assumption for the cases with strong stability (i.e.  $Zi \gg 1$ ).  
 373 The resultant expressions of  $A$  and  $B$  are very simple, which involves only four  
 374 empirical constants, i.e.  $(a_1, b_1, c_1, c_2)$ . The values of these empirical constants

are determined using a least-squares fitting procedure with the simulation data of Liu et al. (2021a) with a limited range of  $u_*/G$ .

To demonstrate the validity of the GDL over a wider range of the geostrophic drag coefficient ( $u_*/G = [0.019, 0.047]$ ) than considered previously (Liu et al. 2021a), we performed 19 simulation cases in which we simultaneously vary the free-atmosphere lapse rate, the latitude, the geostrophic wind, and the roughness length. The validity of the GDL over an extended range of  $u_*/G$  is thus confirmed by the nearly perfect collapse of the GDL coefficients  $A$  and  $B$  obtained from carefully performed LES to a single curve when plotted against the Zilitinkevich number  $Zi$ . In addition, we show through LES that the GDL with the simplified parameterization of  $A$  and  $B$  derived in the limit  $Zi \gg 1$  accurately captures the geostrophic drag coefficient and the cross-isobaric angle for both the moderate and high values of  $Zi$  considered by Liu et al. (2021a,b) and the present study.

Our findings are relevant for meteorological applications such as wind energy. For example, Li et al. (2022) showed that the GDL also applies for flows over extended wind farms, but the  $A$  and  $B$  values are different from that over flat terrains. Based on this finding, the authors proposed an analytical model of fully developed wind farms in CNBLs, and found that the theoretically predicted wind farm power output agrees well with the numerical simulations. Updating the parametrization of  $A$  and  $B$  in the original GDL by Zilitinkevich and Esau (2005) is challenging as it involves updating numerous empirical constants. Therefore, Li et al. (2022) had to numerically fit  $A$  and  $B$  coefficients rather than directly updating the GDL coefficients. While this approach is practical, it limits theoretical exploration and analysis. The GDL parametrization we provide offers more flexibility and applicability for a variety of flow scenarios, including wind farms and canopy flows. This adaptability may facilitate further theoretical exploration and analysis of such situations where the GDL can be applied.

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